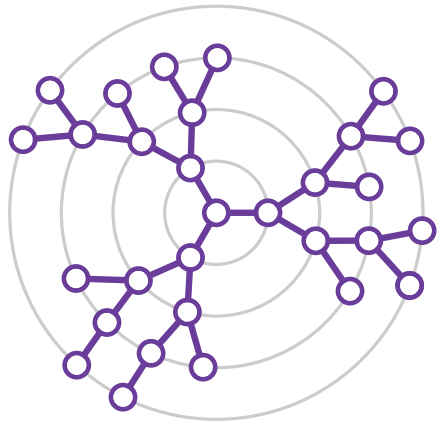
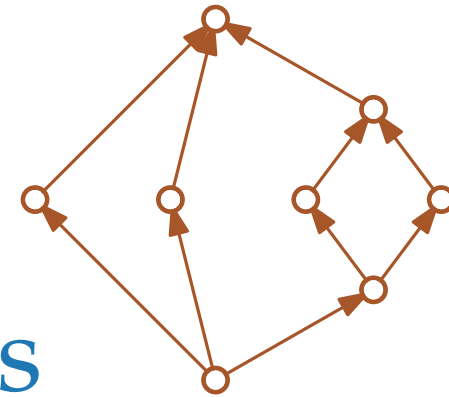


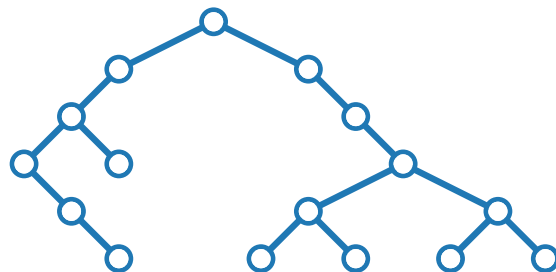
Visualization of Graphs

Lecture 2:

Drawing Trees and Series-Parallel Graphs



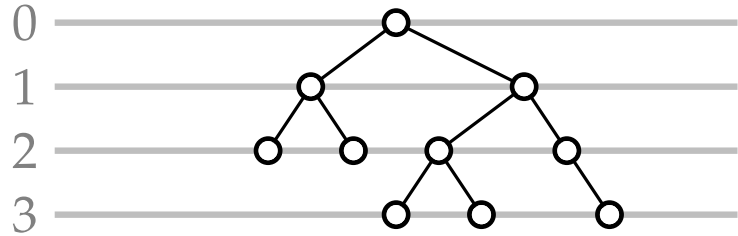
Part I: Layered Drawings



Philipp Kindermann

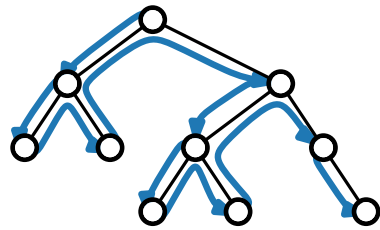
First Grid Layout of Binary Trees

1. Choose y -coordinates: $y(u) = \text{depth}(u)$

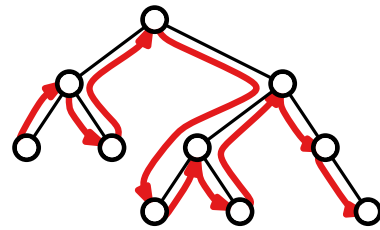


2. Choose x -coordinates:

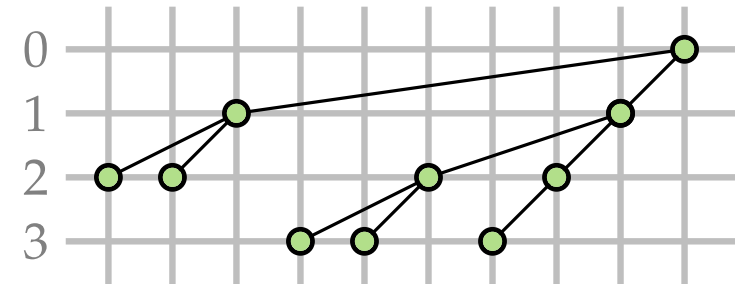
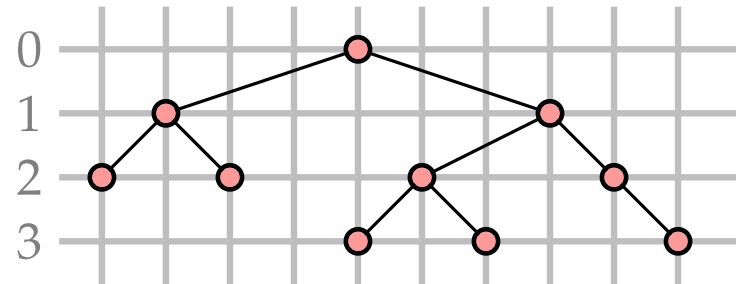
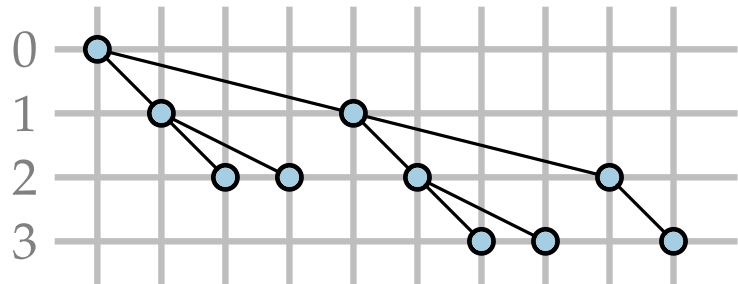
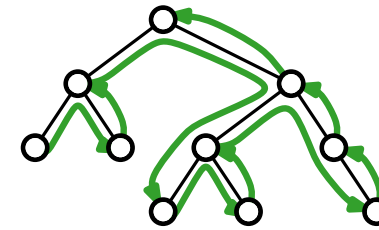
preorder



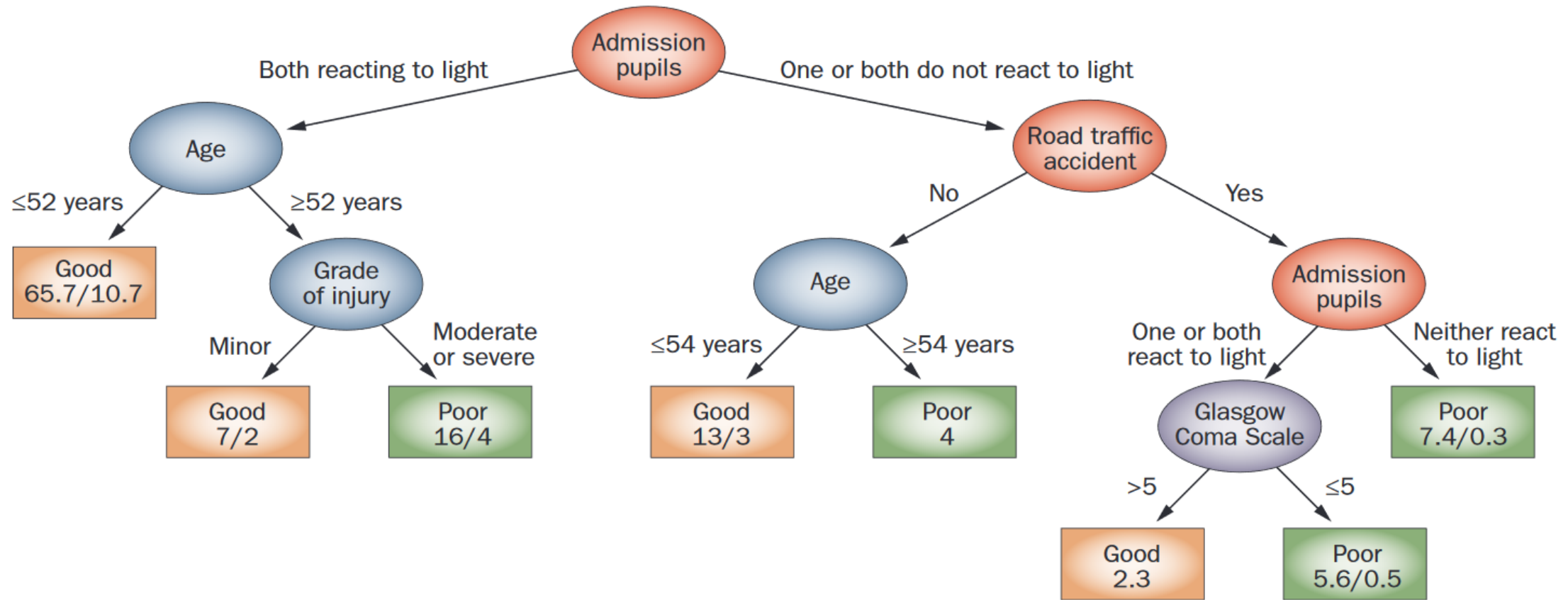
inorder



postorder



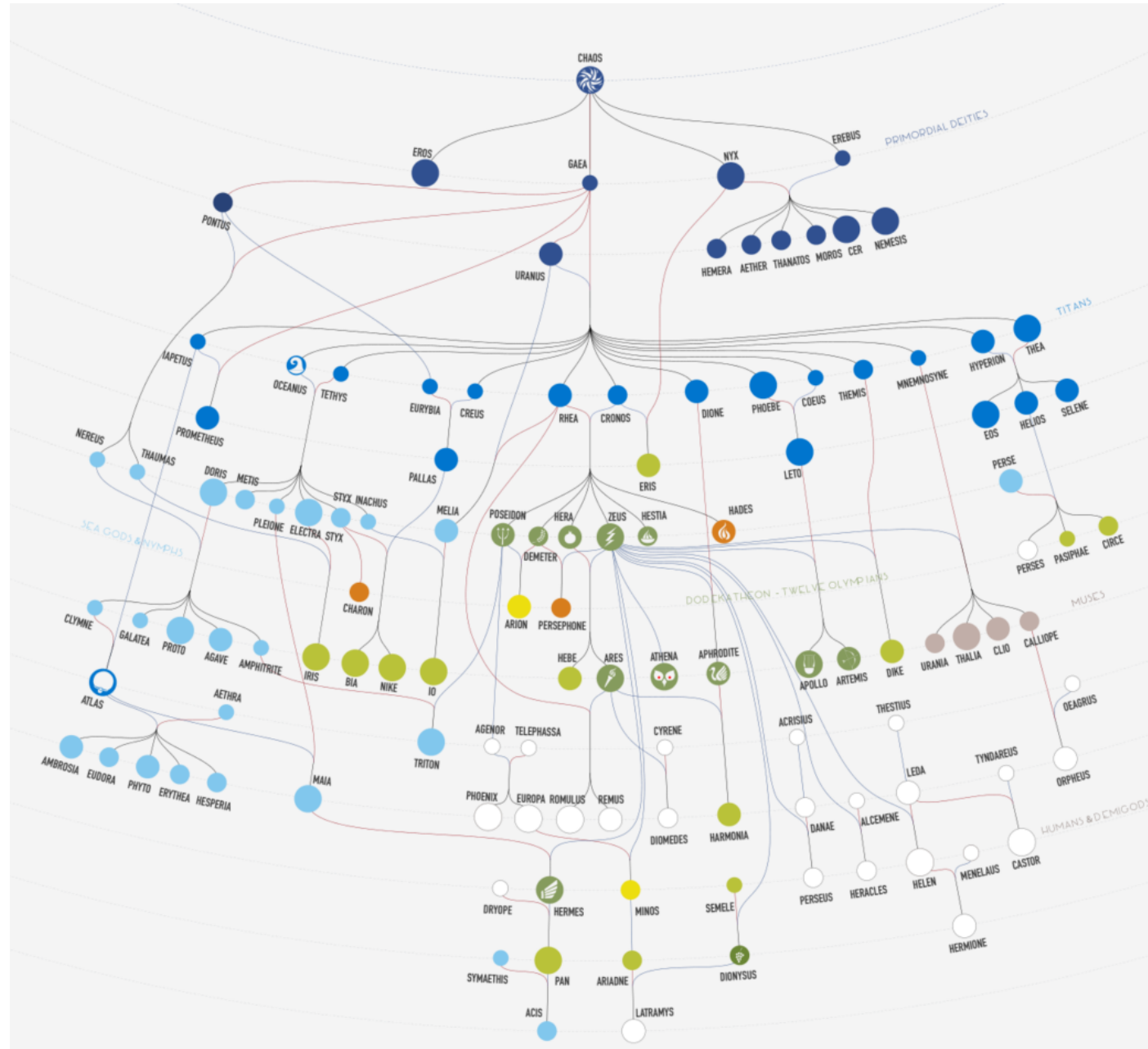
Layered Drawings – Applications



Decision tree for outcome prediction after traumatic brain injury

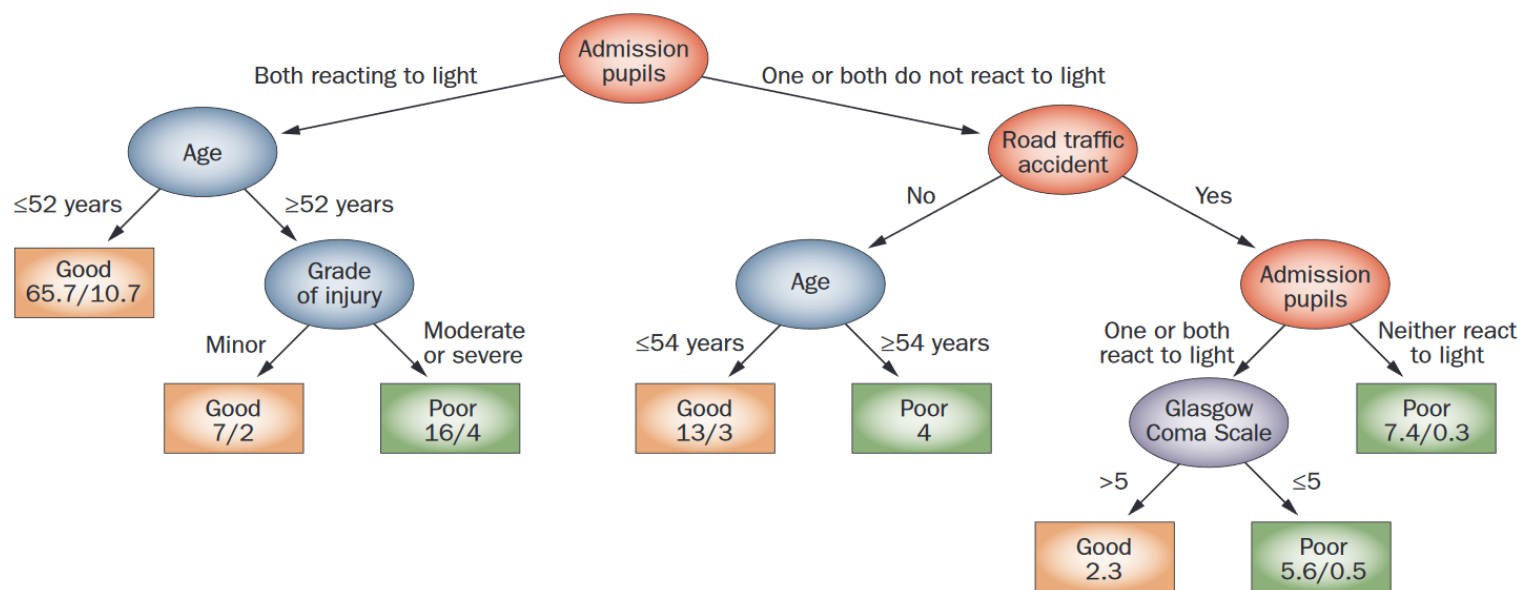
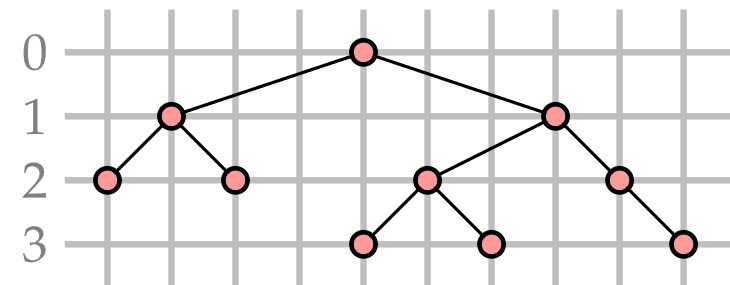
Source: Nature Reviews Neurology

Layered Drawings – Applications

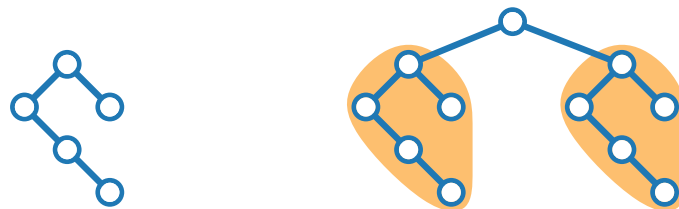


J. Klawitter, T. Mchedlidze, *Link:* go.uniwue.de/myth-poster

Layered Drawings – Drawing Style



- What are properties of the layout?
- What are the drawing conventions?
- What are aesthetics to optimize?



Drawing conventions

- Vertices lie on layers and have integer coordinates
- Parent centered above children
- Edges are straight-line segments
- Isomorphic subtrees have identical drawings

Drawing aesthetics

- Area
- Symmetries

Layered Drawings – Algorithm

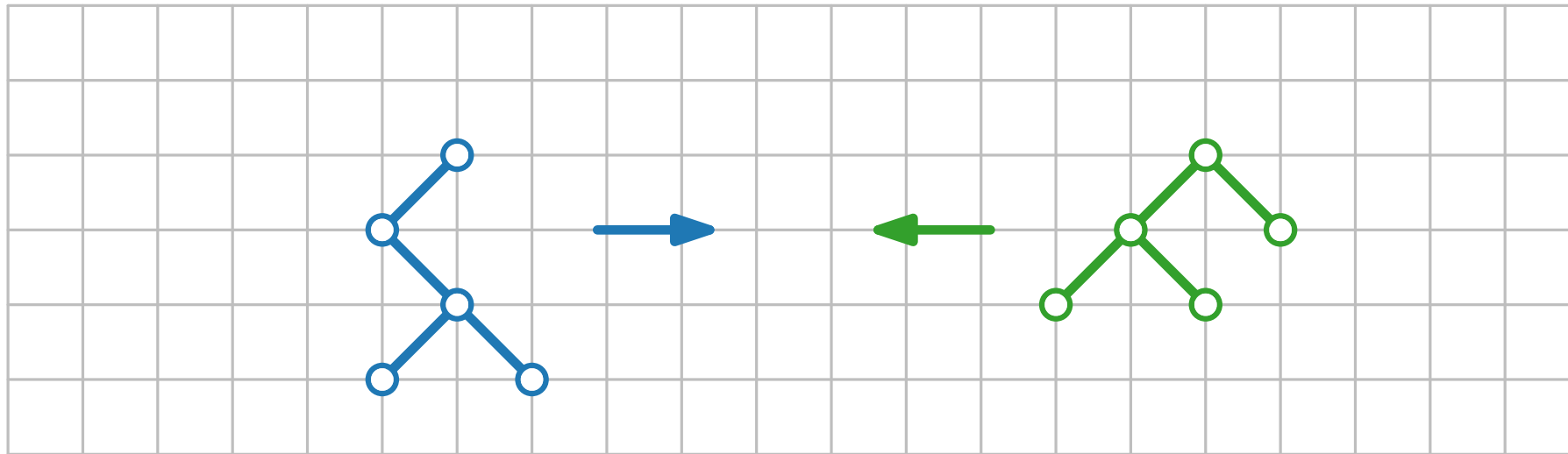
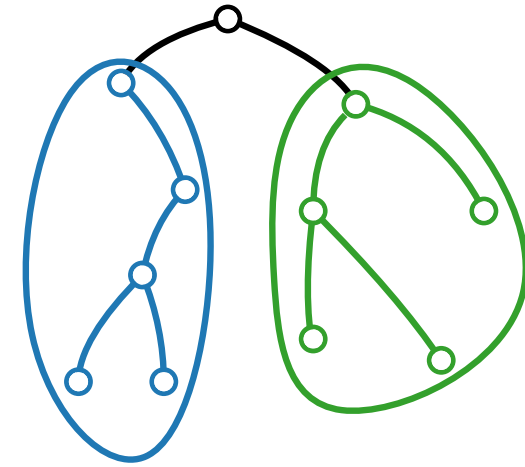
Input: A binary tree T

Output: A layered drawing of T

Base case: A single vertex \circ

Divide: Recursively apply the algorithm to draw the left and right subtrees

Conquer:



Layered Drawings – Algorithm

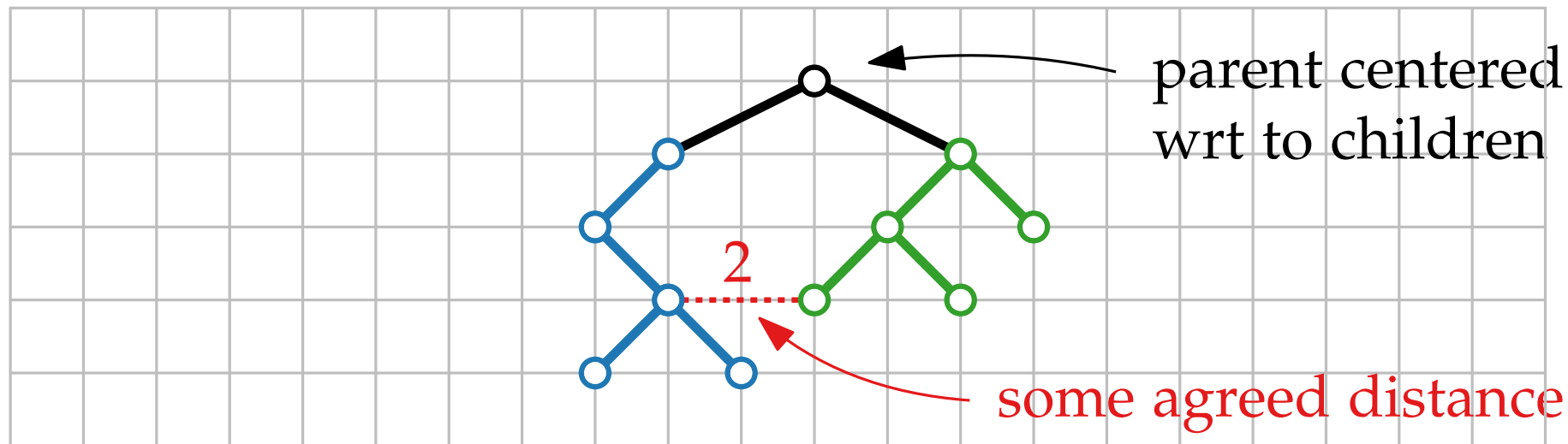
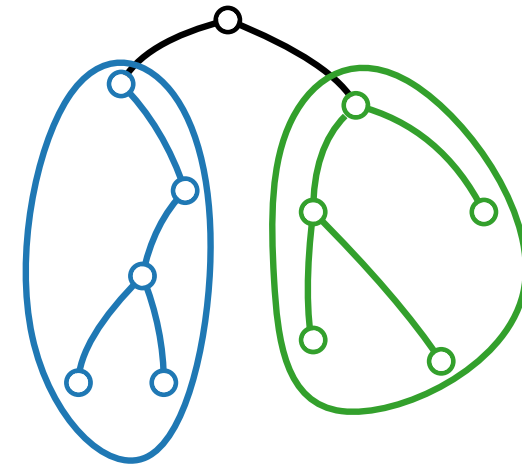
Input: A binary tree T

Output: A layered drawing of T

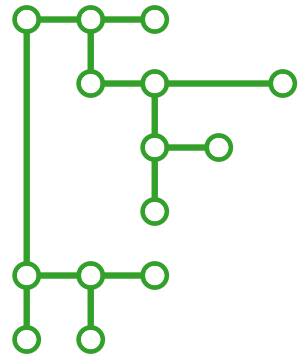
Base case: A single vertex \circ

Divide: Recursively apply the algorithm to draw the left and right subtrees

Conquer:



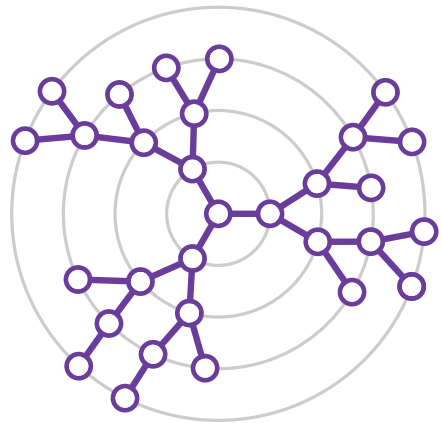
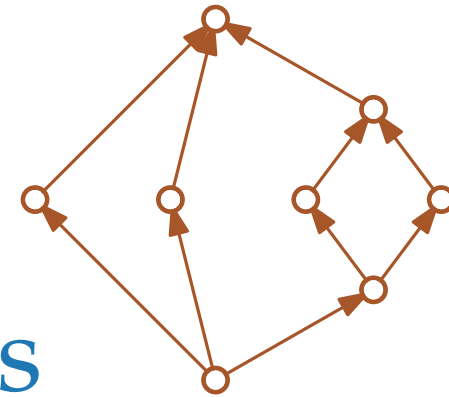
sometimes 3 apart for grid drawing!



Visualization of Graphs

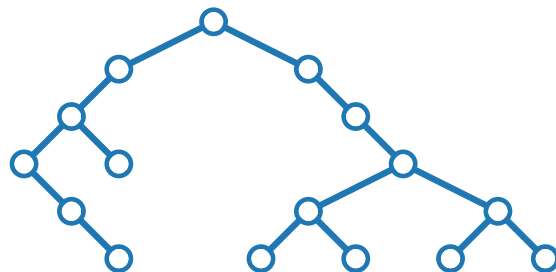
Lecture 2:

Drawing Trees and Series-Parallel Graphs



Part II:

Layered Drawings – Algorithmic Details



Philipp Kindermann

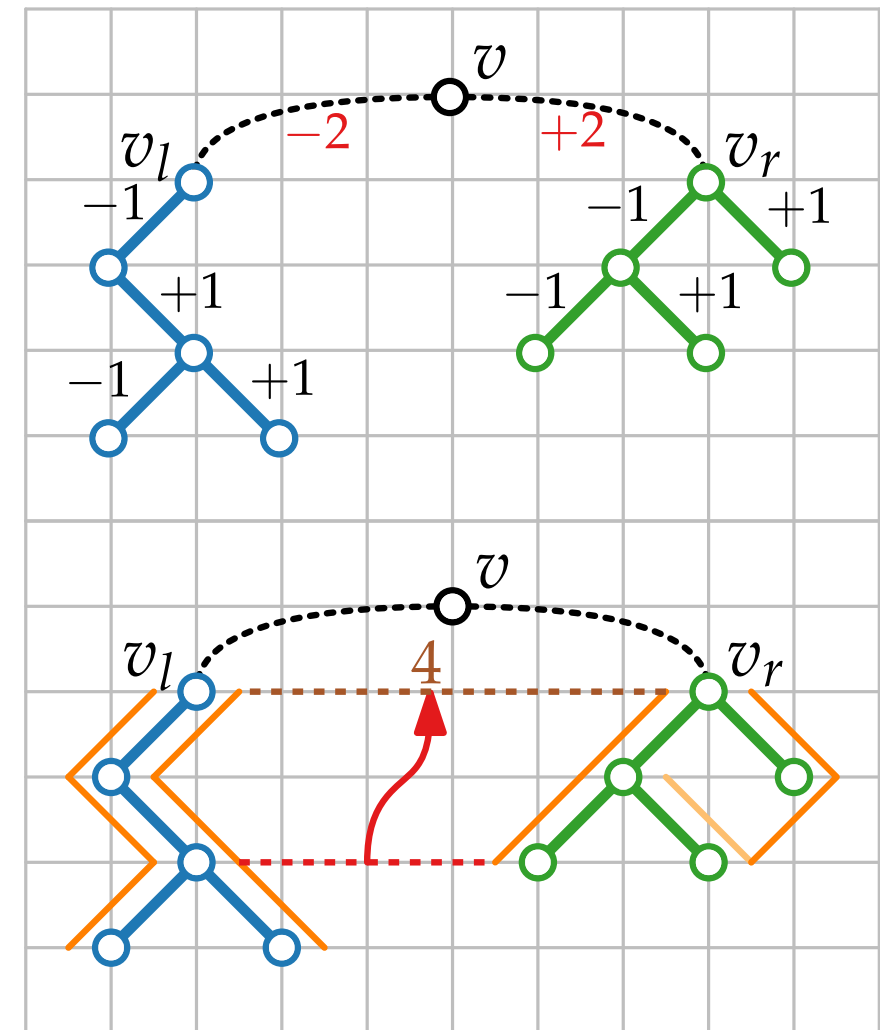
Layered Drawings – Algorithm Details

Phase 1 – postorder traversal:

- For each vertex compute horizontal displacement of left and right child
- $\mathbf{x\text{-offset}(v_l)} = -\lceil \frac{d_v}{2} \rceil$, $\mathbf{x\text{-offset}(v_r)} = \lceil \frac{d_v}{2} \rceil$
- At vertex u (below v) store left and right **contour** of subtree $T(u)$
- Contour is linked list of vertex coordinates/offsets
- Find $d_v = \text{min. horiz. distance between } v_l \text{ and } v_r$

Phase 2 – preorder traversal:

- Compute x- and y-coordinates



Layered Drawings – Algorithm Details

Phase 1 – postorder traversal:

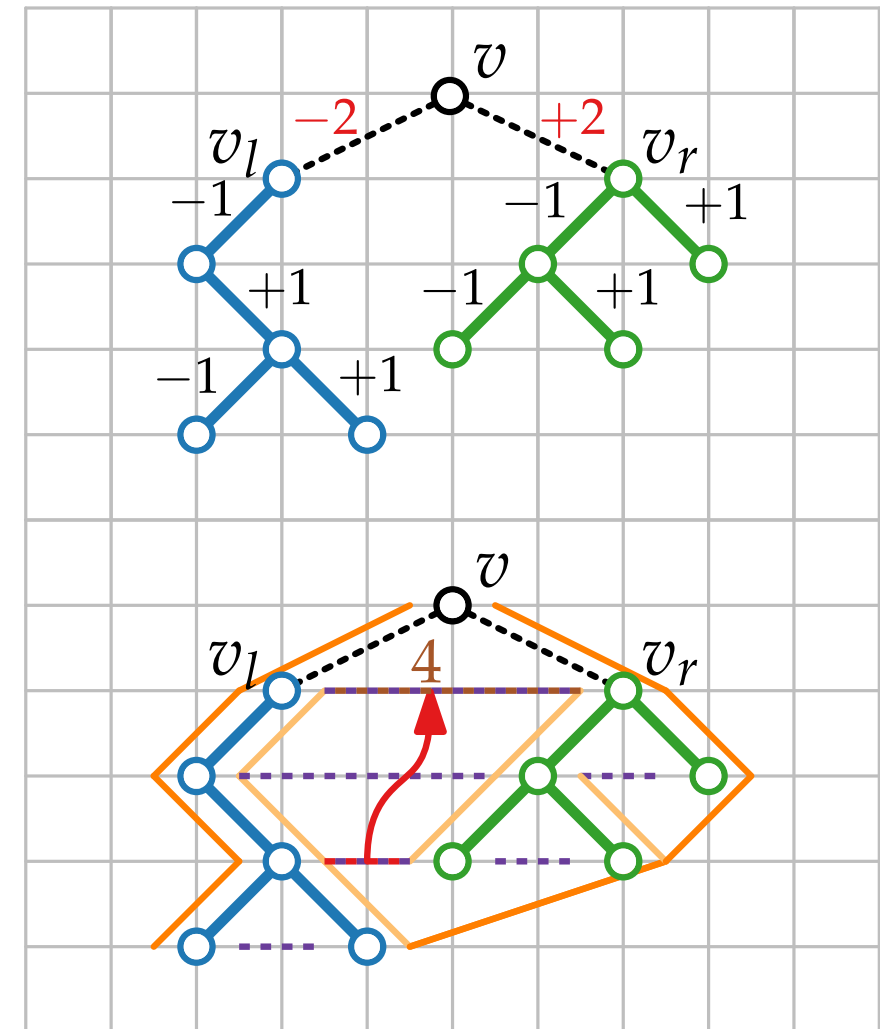
- For each vertex compute horizontal displacement of left and right child
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- At vertex u (below v) store left and right **contour** of subtree $T(u)$
- Contour is linked list of vertex coordinates/offsets
- Find $d_v = \text{min. horiz. distance between } v_l \text{ and } v_r$

Phase 2 – preorder traversal:

- Compute x- and y-coordinates

Runtime?

- How often do we have to **walk along a contour**?



$\Rightarrow \mathcal{O}(n)$

Layered Drawings – Result

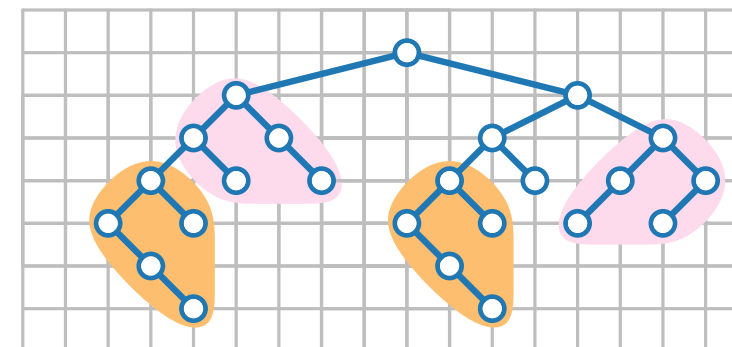
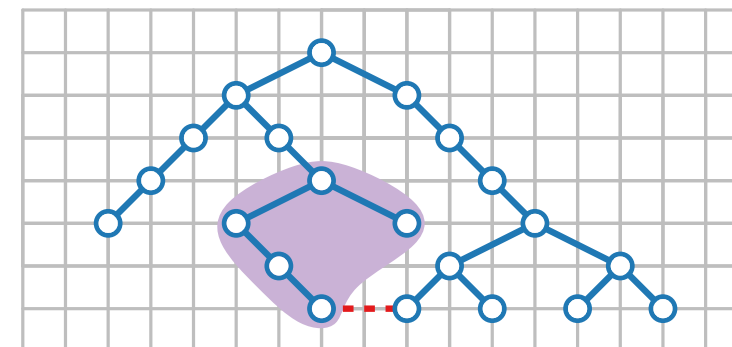
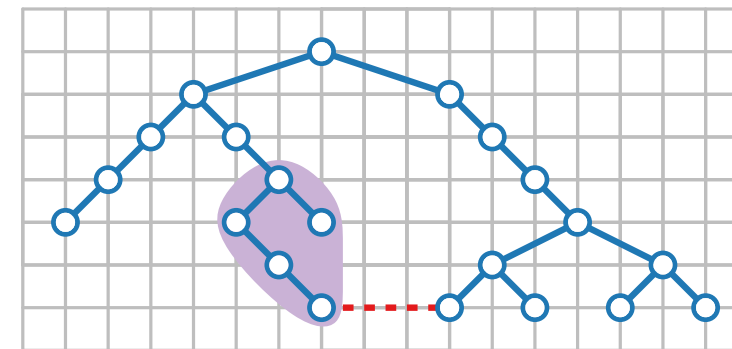
Theorem.

[Reingold & Tilford '81]

Let T be a binary tree with n vertices. We can construct a drawing Γ of T in $\mathcal{O}(n)$ time, such that:

- Γ is planar, straight-line and strictly downward
- Γ is layered: y-coordinate of vertex v is $-\text{depth}(v)$
- Horizontal and Vertical distances are at least 1
- Each vertex is centred wrt its children
- Area of Γ is in $\mathcal{O}(n^2)$ – but not optimal!
- Simply isomorphic subtrees have congruent drawings, up to translation
- Axially isomorphic subtrees have congruent drawings, up to translation and reflection

NP-hard

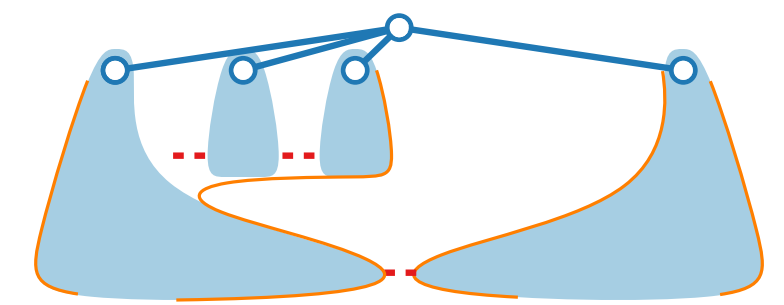
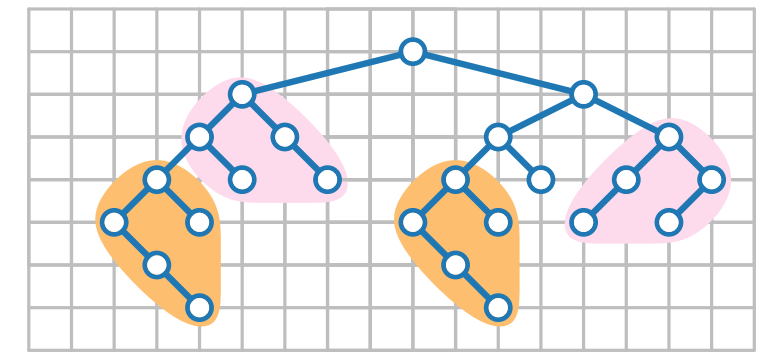
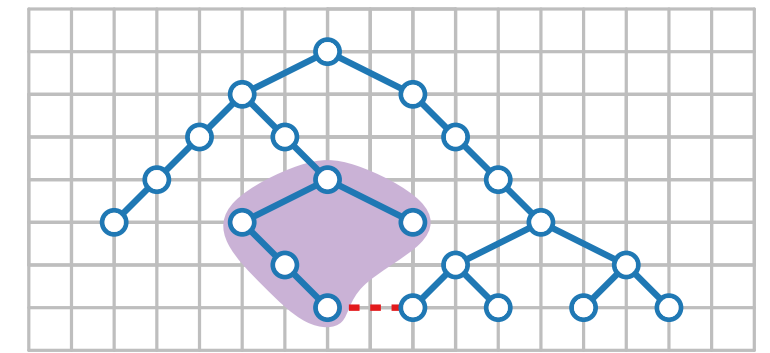
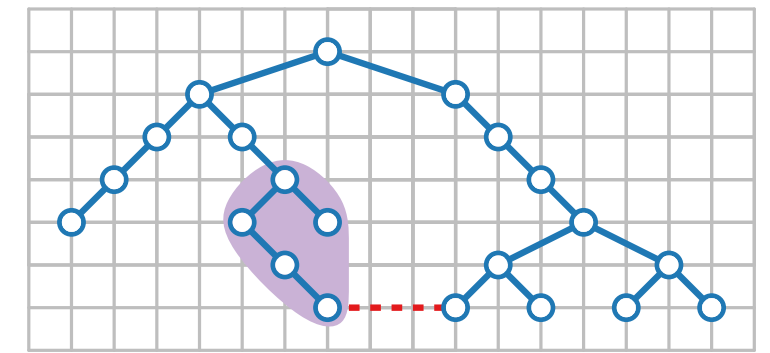


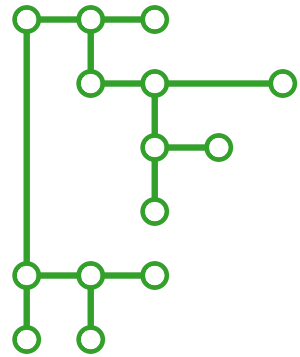
Layered Drawings – Result

Theorem. [Reingold & Tilford '81]

Let T be a ~~binary~~ ^{rooted} tree with n vertices. We can construct a drawing Γ of T in $\mathcal{O}(n)$ time, such that:

- Γ is planar, straight-line and strictly downward
- Γ is layered: y-coordinate of vertex v is $-\text{depth}(v)$
- Horizontal and Vertical distances are at least 1
- Each vertex is centred wrt its children
- Area of Γ is in $\mathcal{O}(n^2)$ – but not optimal! NP-hard
- Simply isomorphic subtrees have congruent drawings, up to translation
- ~~■ Axially isomorphic subtrees have congruent drawings, up to translation and reflection~~

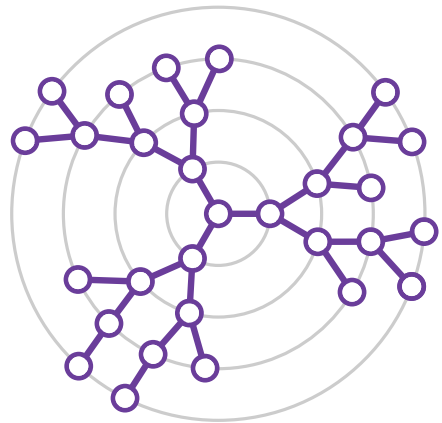
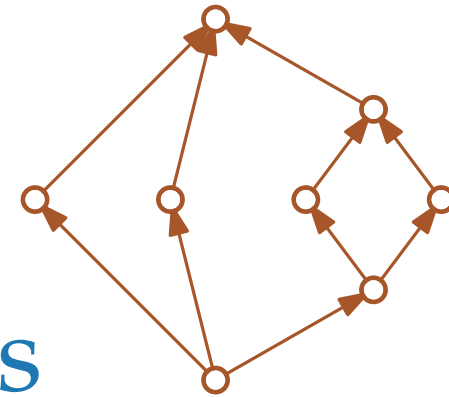




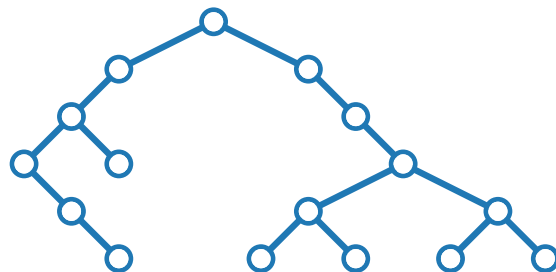
Visualization of Graphs

Lecture 2:

Drawing Trees and Series-Parallel Graphs



Part III: HV-Drawings



Philipp Kindermann

HV-Drawings – Algorithm

Input: A binary tree T

Output: An HV-drawing of T

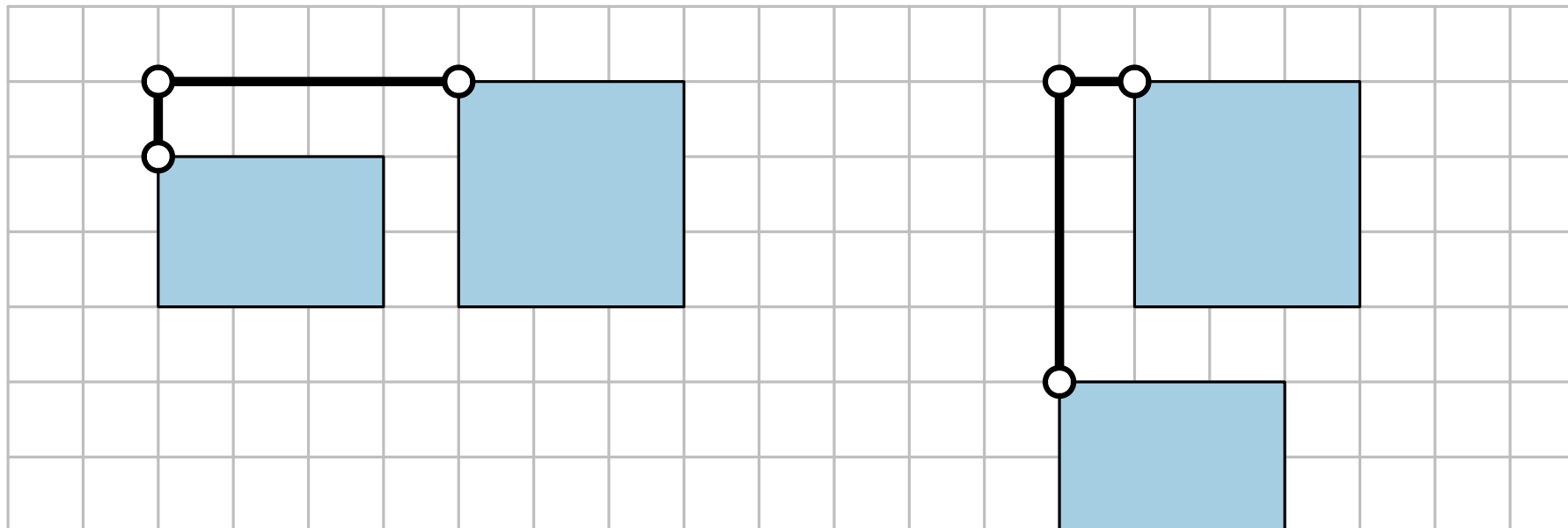
Base case: 

Divide: Recursively apply the algorithm to draw the left and right subtrees

Conquer:

horizontal combination

vertical combination



HV-Drawings – Right-Heavy HV-Layout

Right-heavy approach

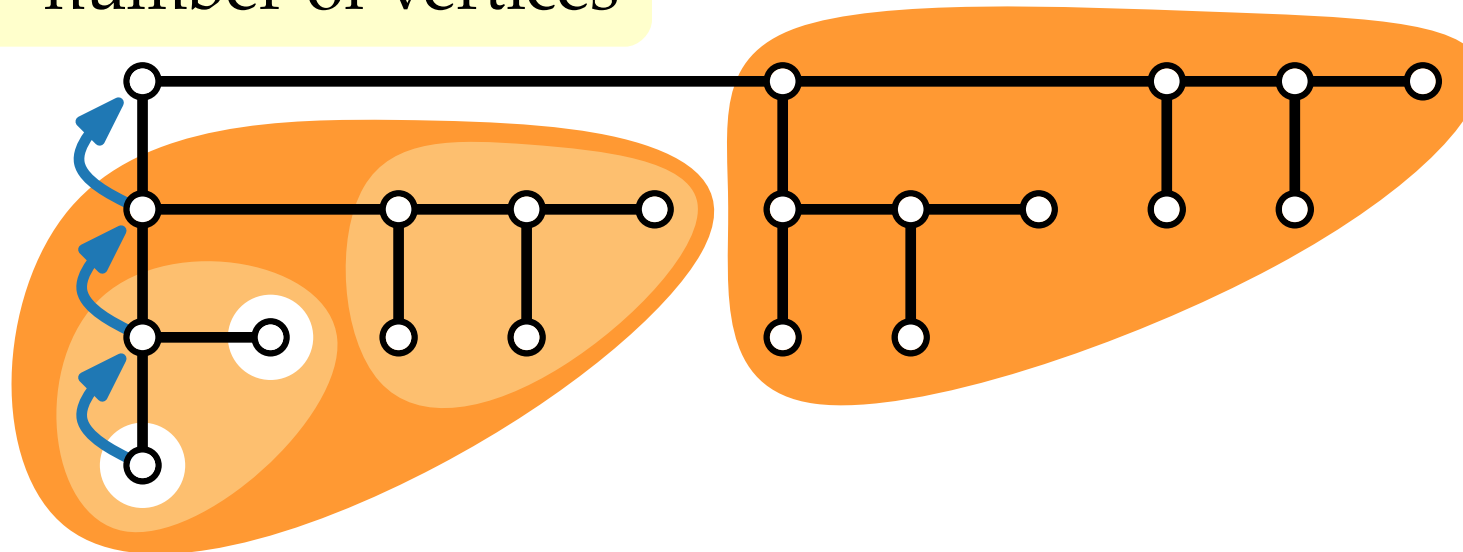
- Always apply horizontal combination
 - Place the larger subtree to the right
- Size of subtree := number of vertices

How to implement this
in **linear time**?

at least $\cdot 2$

at least $\cdot 2$

at least $\cdot 2$



Lemma. Let T be a binary tree. The drawing constructed by the right-heavy approach has

- width at most $n - 1$ and
- height at most $\log n$.

HV-Drawings – Result

Theorem.

Let T be a binary tree with n vertices. The right-heavy algorithm constructs in $O(n)$ time a drawing Γ of T s.t.:

- Γ is an HV-drawing
(planar, orthogonal, strictly right-/downward)
- Width is at most $n - 1$
- Height is at most $\log n$
- Area is in $\mathcal{O}(n \log n)$
- Simply and axially isomorphic subtrees have congruent drawings up to translation

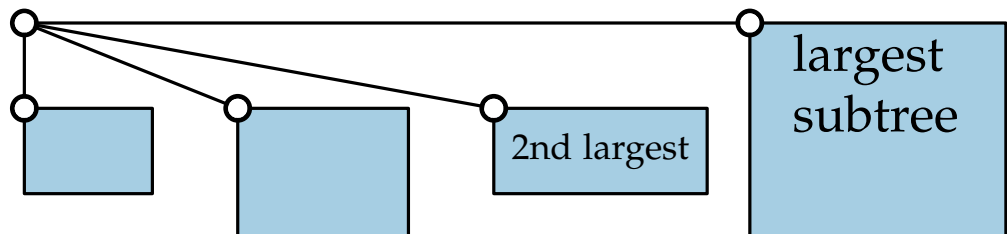
HV-Drawings – Result

Theorem. ~~rooted~~

Let T be a ~~binary~~ tree with n vertices. The right-heavy algorithm constructs in $O(n)$ time a drawing Γ of T s.t.:

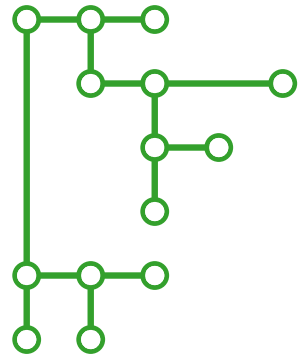
- Γ is an HV-drawing
(planar, ~~orthogonal~~, strictly right-/downward)
- Width is at most $n - 1$
- Height is at most $\log n$
- Area is in $\mathcal{O}(n \log n)$
- Simply and axially isomorphic subtrees have congruent drawings up to translation

General rooted tree



Optimal area?

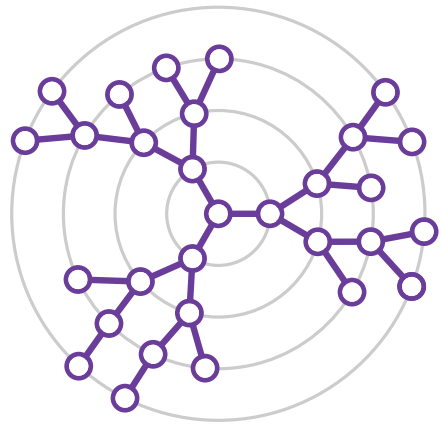
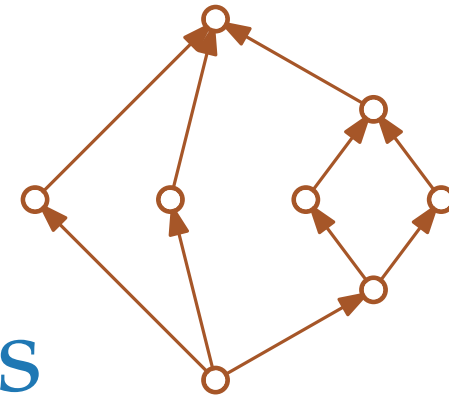
Not with divide & conquer approach, but can be computed with Dynamic Programming.



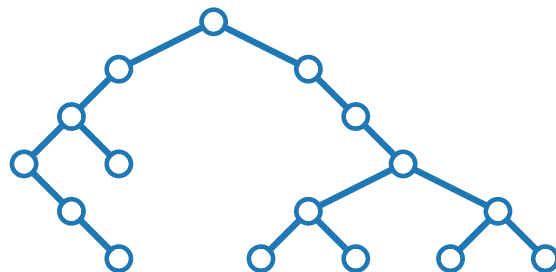
Visualization of Graphs

Lecture 2:

Drawing Trees and Series-Parallel Graphs

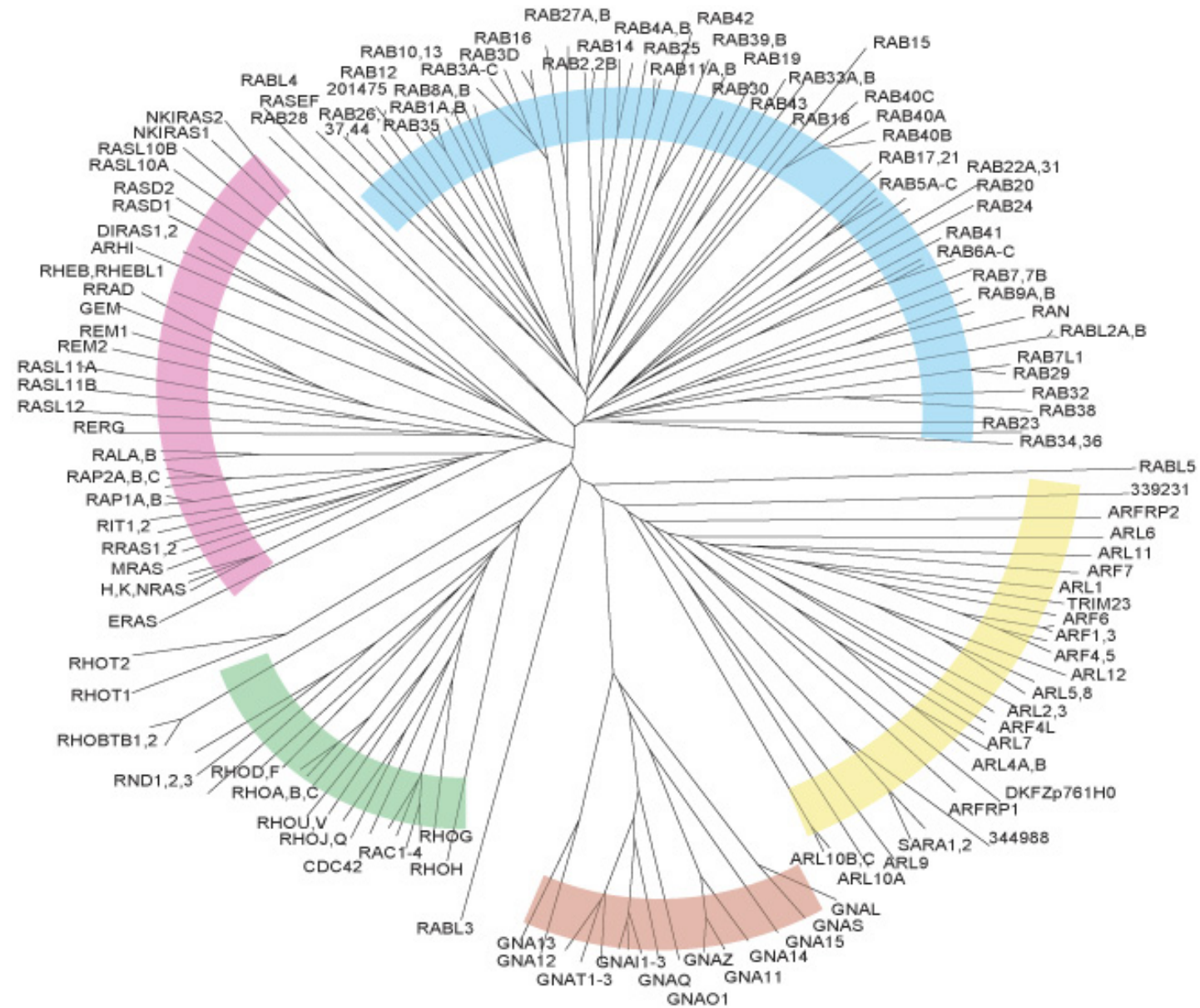


Part IV: Radial Layouts



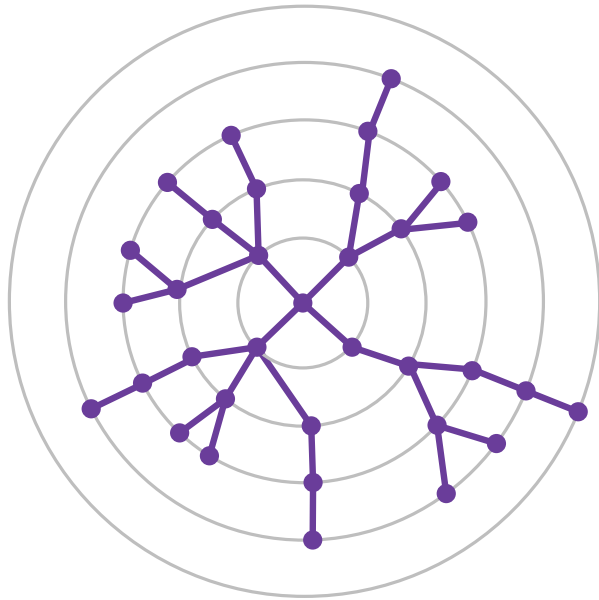
Philipp Kindermann

Radial Layouts – Applications



Phylogenetic tree
by Colicelli, ScienceSignaling, 2004

Radial Layouts – Drawing Style



Drawing conventions

- Vertices lie on circular layers according to their depth
- Drawing is planar

Drawing aesthetics

- Distribution of the vertices

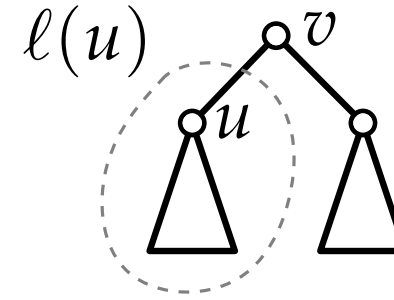
How can an algorithm optimize the distribution of the vertices?

Radial Layouts – Algorithm Attempt

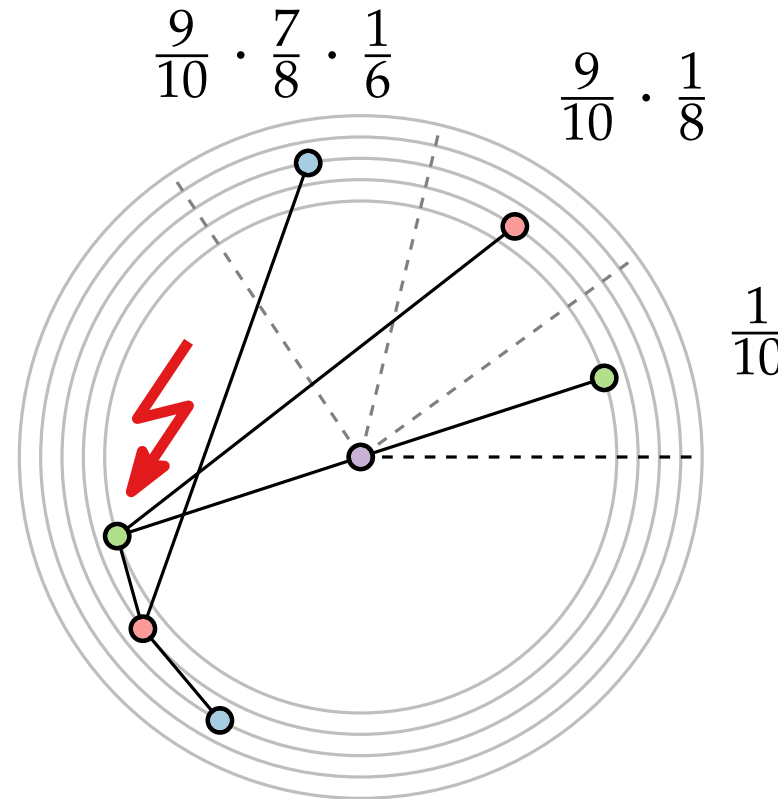
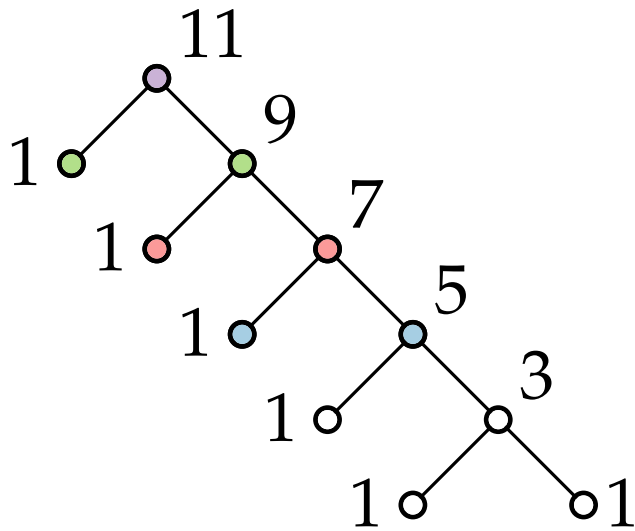
Idea

- Reserve area corresponding to size $\ell(u)$ of $T(u)$:

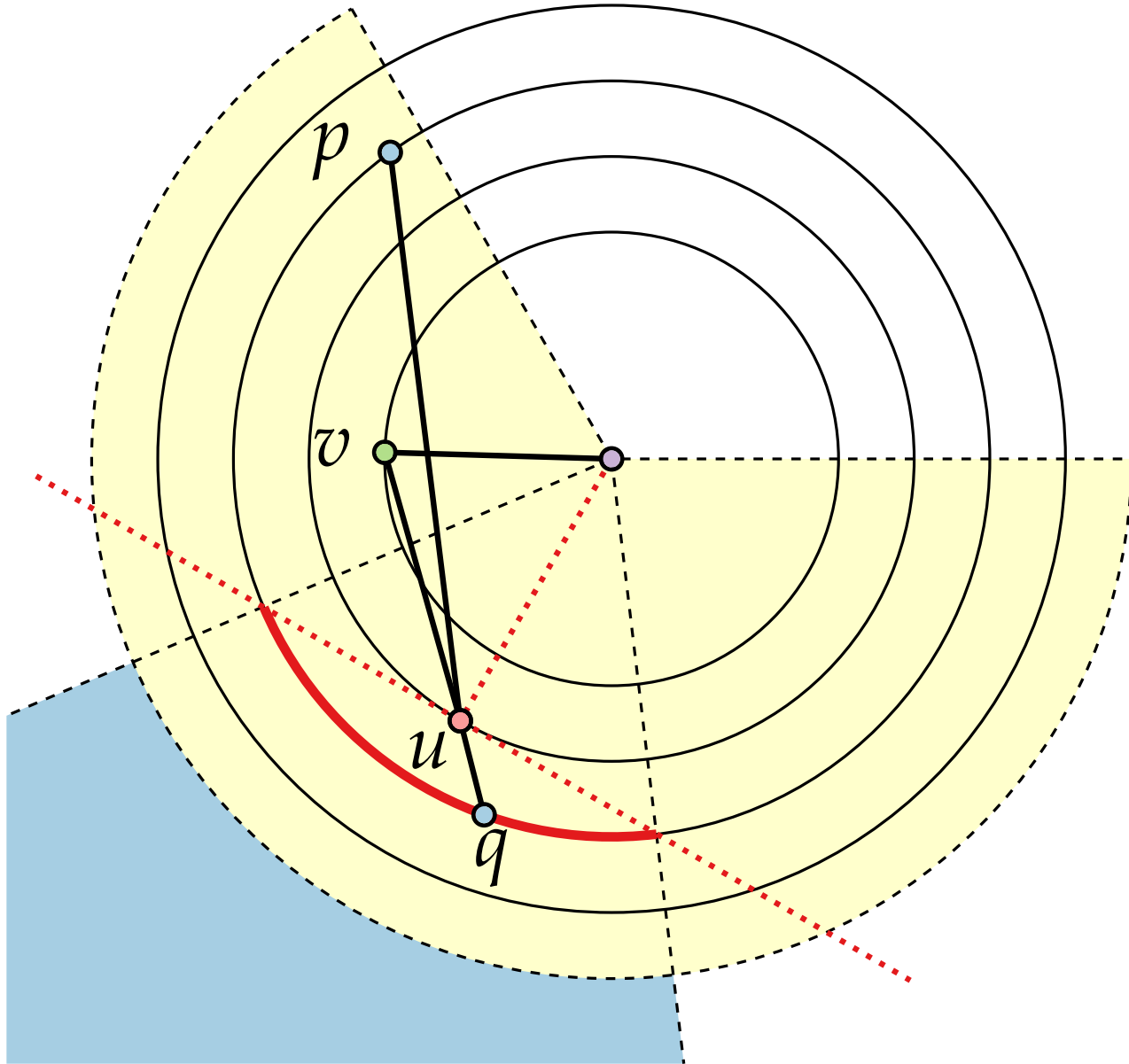
$$\tau_u = \frac{\ell(u)}{\ell(v) - 1}$$



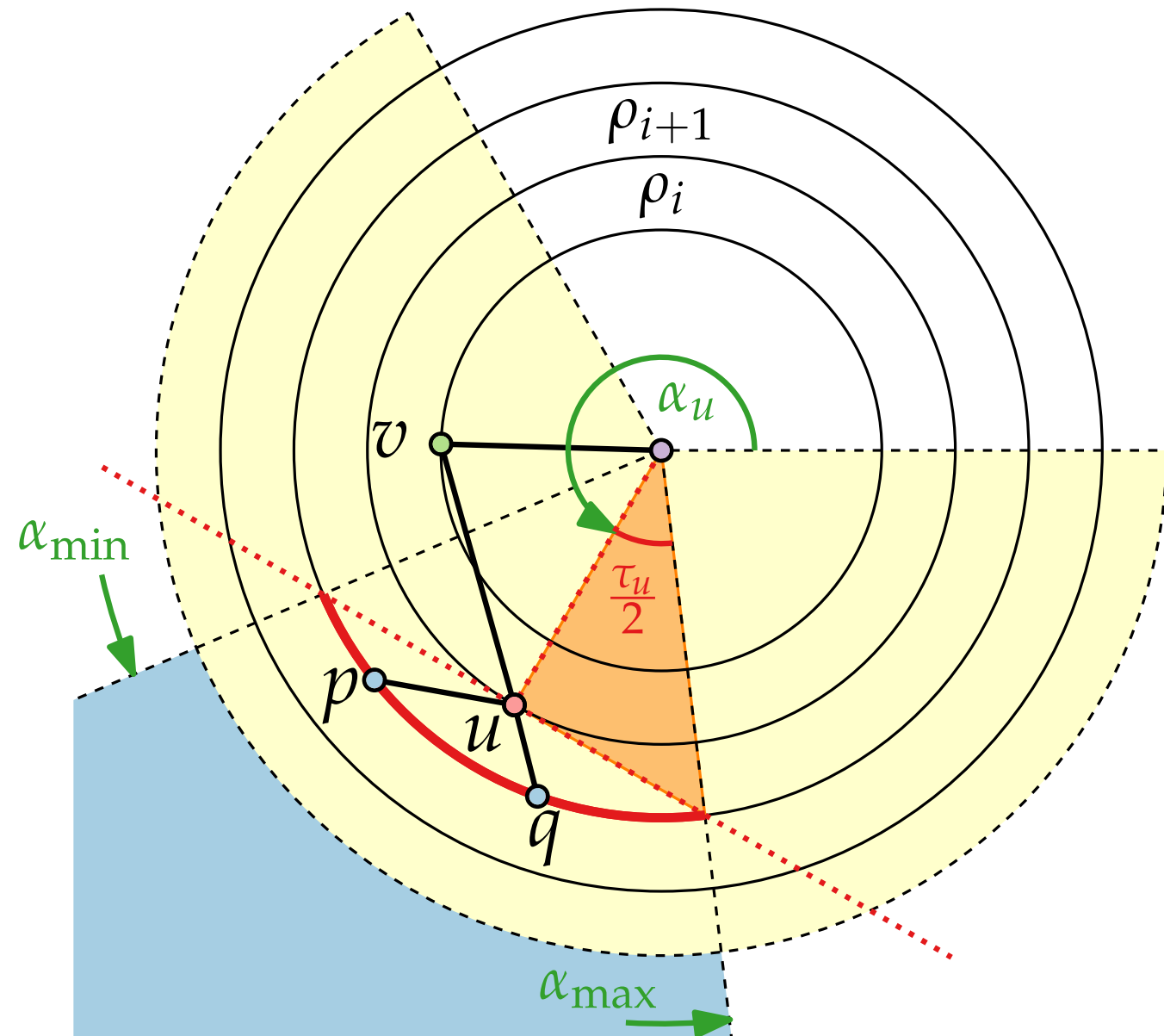
- Place u in middle of area



Radial Layouts – How To Avoid Crossings



Radial Layouts – How To Avoid Crossings



- τ_u – angle of the wedge corresponding to vertex u
- $\ell(u)$ – number of nodes in the subtree rooted at u
- ρ_i – radius of layer i
- $\cos \frac{\tau_u}{2} = \frac{\rho_i}{\rho_{i+1}}$
- $\tau_u = \min \left\{ \frac{\ell(u)}{\ell(v)-1}, 2 \arccos \frac{\rho_i}{\rho_{i+1}} \right\}$
- Alternative:
 - $\alpha_{\min} = \alpha_u - \arccos \frac{\rho_i}{\rho_{i+1}}$
 - $\alpha_{\max} = \alpha_u + \arccos \frac{\rho_i}{\rho_{i+1}}$

Radial Layouts – Pseudocode

RadialTreeLayout(tree T , root $r \in T$, radii $\rho_1 < \dots < \rho_k$)

begin

$postorder(r)$

$preorder(r, 0, 0, 2\pi)$

return $(d_v, \alpha_v)_{v \in V(T)}$

 // vertex pos./polar coord.

$postorder(\text{vertex } v)$

$\ell(v) \leftarrow 1$

foreach child w of v **do**

$postorder(w)$

$\ell(v) \leftarrow \ell(v) + \ell(w)$

$preorder(\text{vertex } v, t, \alpha_{\min}, \alpha_{\max})$

$d_v \leftarrow \rho_t$ //output

$\alpha_v \leftarrow (\alpha_{\min} + \alpha_{\max}) / 2$

if $t > 0$ **then**

$\alpha_{\min} \leftarrow \max\{\alpha_{\min}, \alpha_v - \arccos \frac{\rho_t}{\rho_{t+1}}\}$

$\alpha_{\max} \leftarrow \min\{\alpha_{\max}, \alpha_v + \arccos \frac{\rho_t}{\rho_{t+1}}\}$

$left \leftarrow \alpha_{\min}$

foreach child w of v **do**

$right \leftarrow left + \frac{\ell(w)}{\ell(v)-1} \cdot (\alpha_{\max} - \alpha_{\min})$

$preorder(w, t + 1, left, right)$

$left \leftarrow right$

Runtime? $\mathcal{O}(n)$

Correctness? ✓

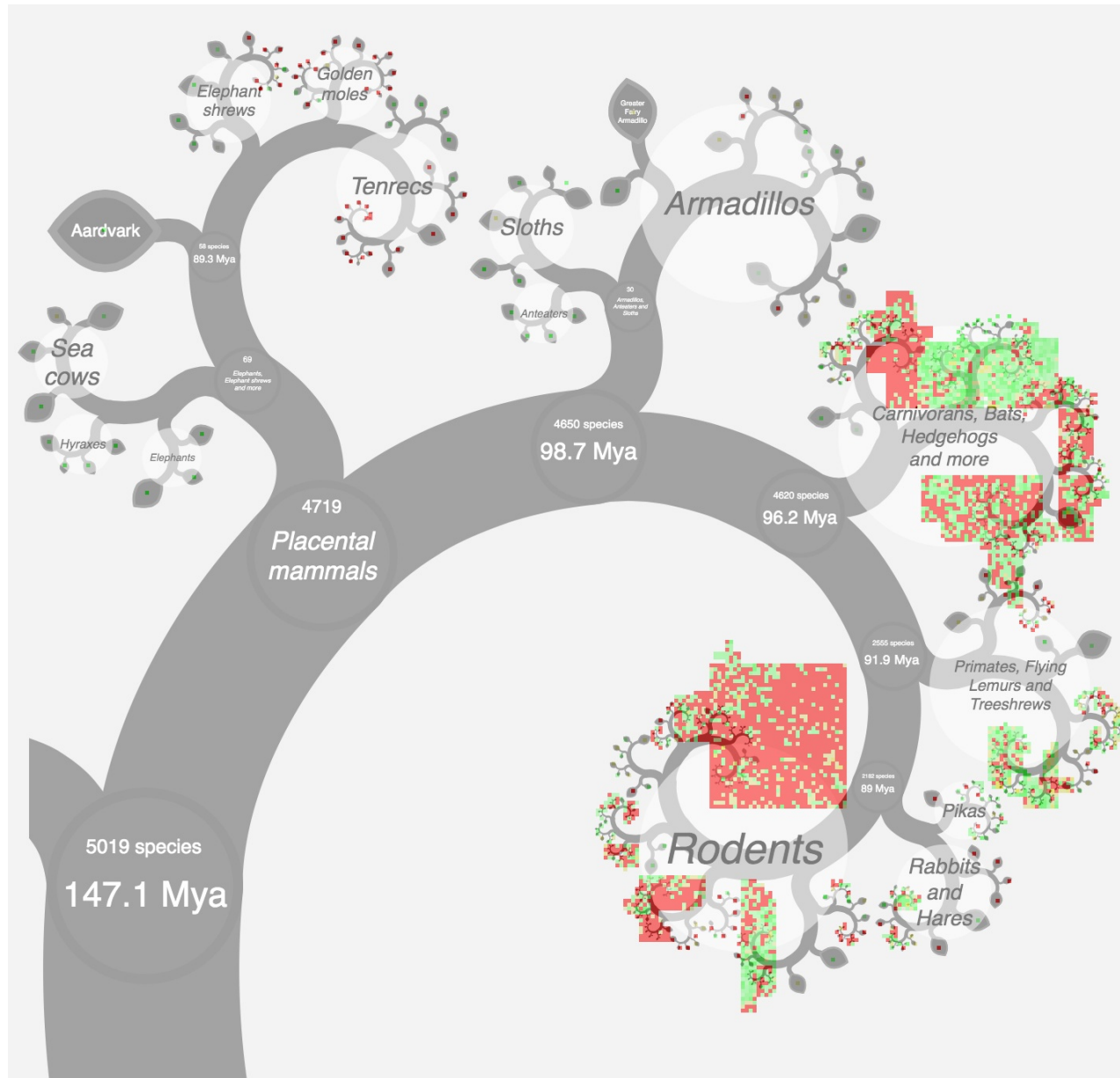
Radial Layouts – Result

Theorem.

Let T be a tree with n vertices. The RadialTreeLayout algorithm constructs in $O(n)$ time a drawing Γ of T s.t.:

- Γ is radial drawing
- Vertices lie on circle according to their depth
- Area quadratic in max degree times height of T
(see [GD Ch. 3.1.3] if interested)

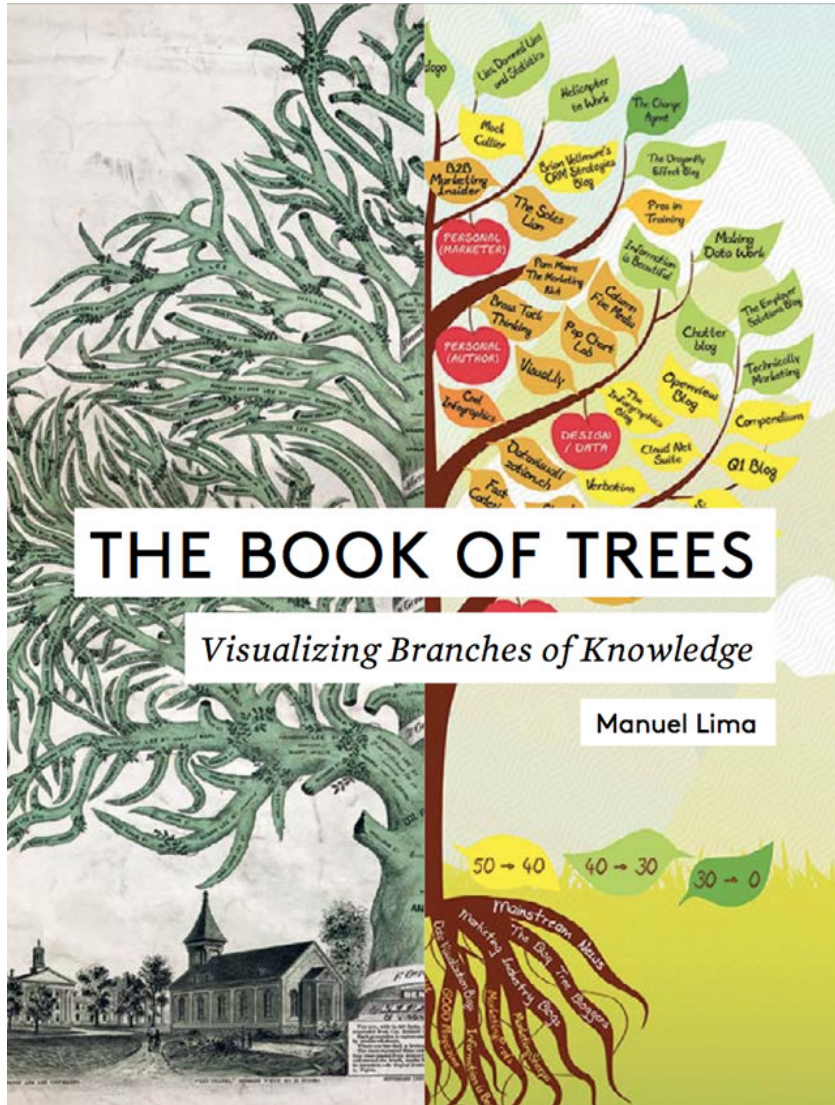
Other Tree Visualization Styles



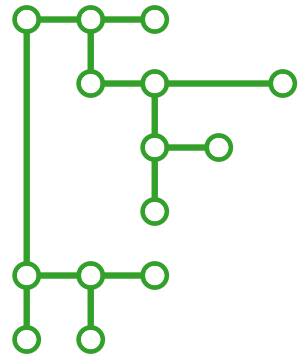
A phylogenetically organised display of data for all placental mammal species.

Fractal layout

Other Tree Visualization Styles



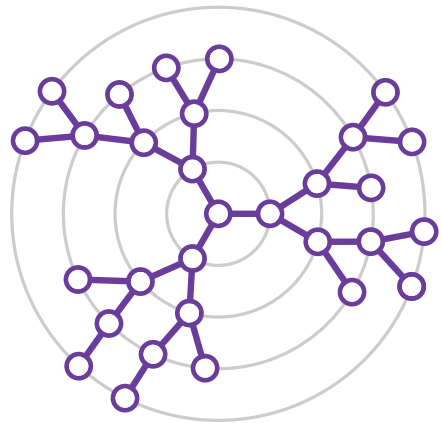
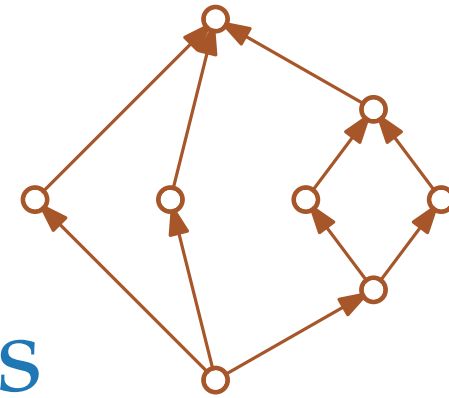
treevis.net



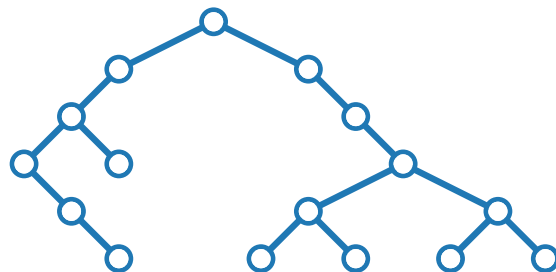
Visualization of Graphs

Lecture 2:

Drawing Trees and Series-Parallel Graphs



Part V: Series-Parallel Graphs

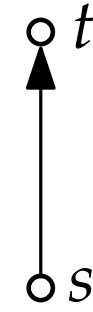


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Series-Parallel Graphs

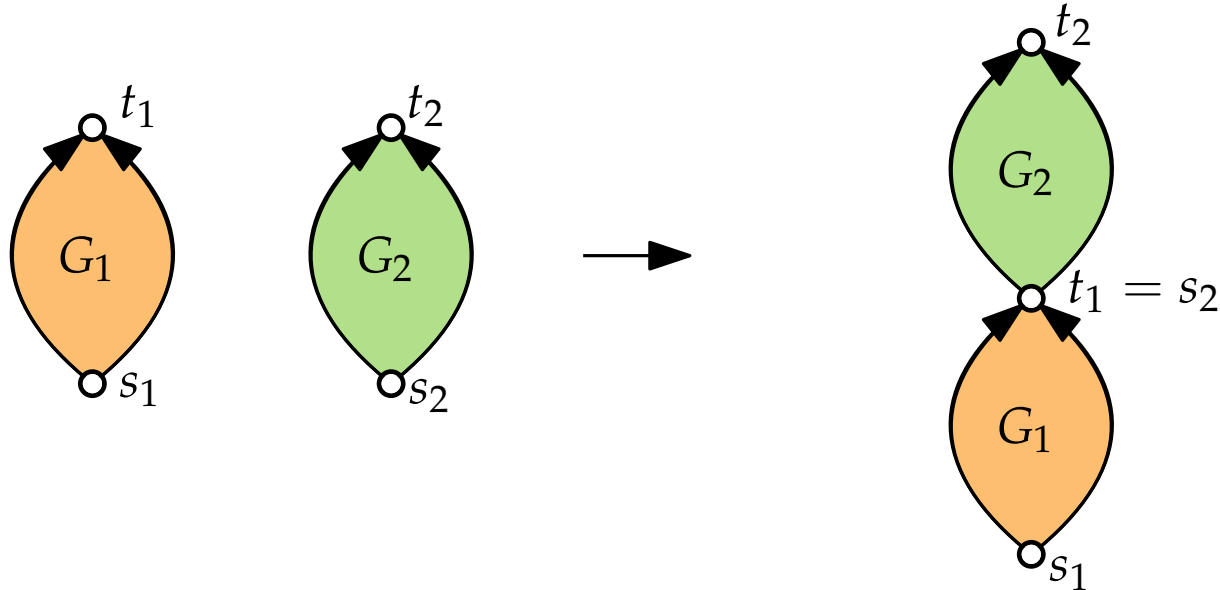
A graph G is **series-parallel**, if

- it contains a single (directed) edge (s, t) , or
- it consists of two series-parallel graphs G_1, G_2 with sources s_1, s_2 and sinks t_1, t_2 that are combined using one of the following rules:

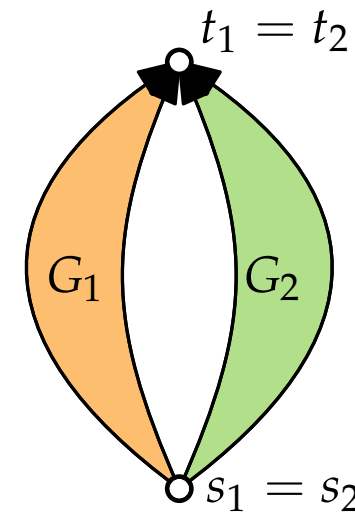


convince yourself
that series-parallel
graphs are planar

Series composition



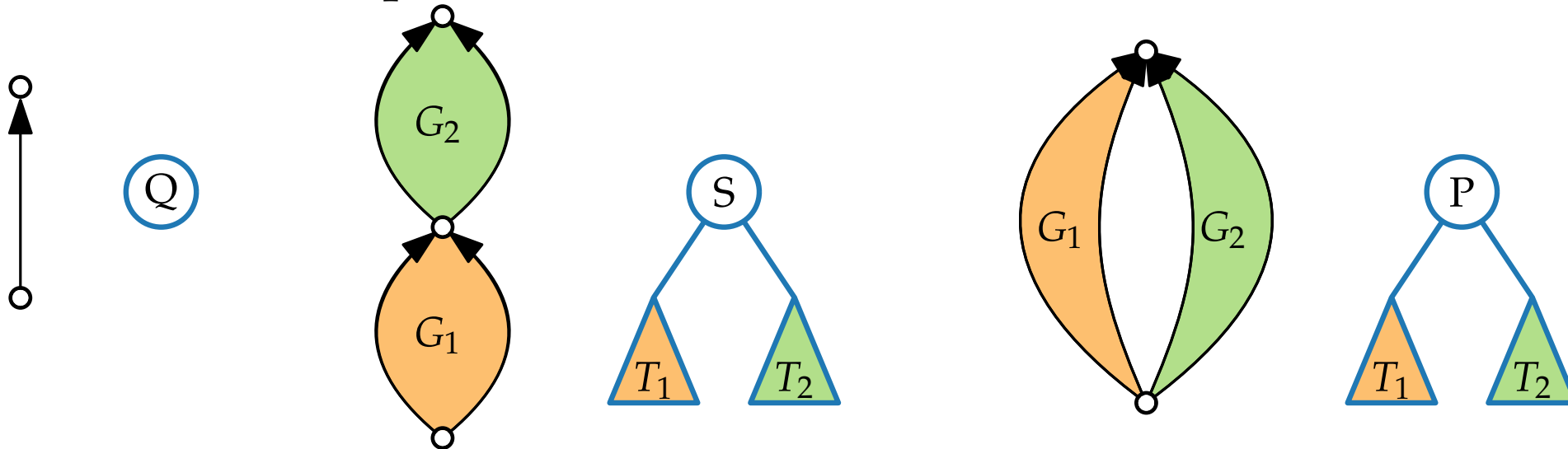
Parallel composition



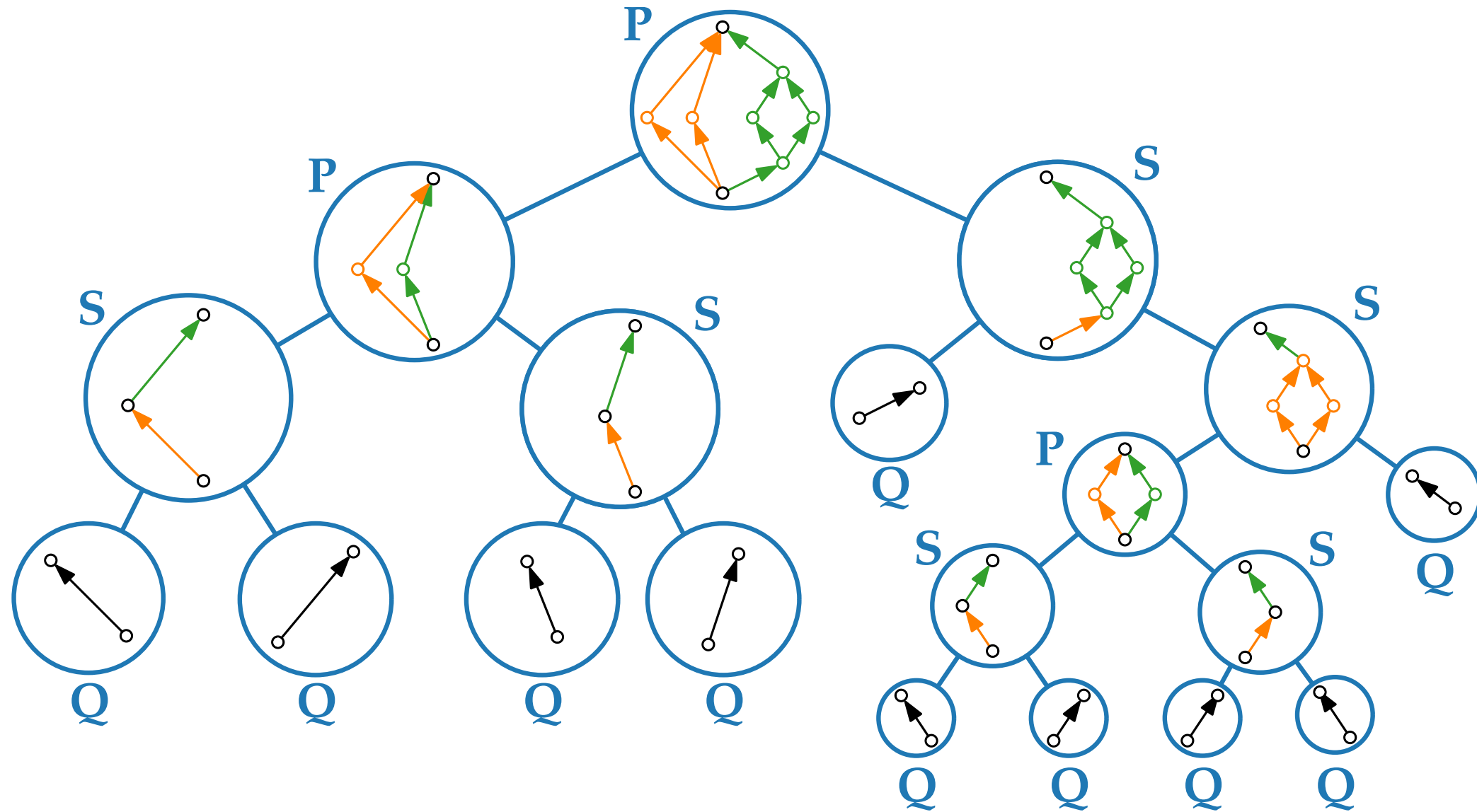
Series-Parallel Graphs – Decomposition Tree

A **decomposition tree** of G is a binary tree T with nodes of three types: **S**, **P** and **Q**-type

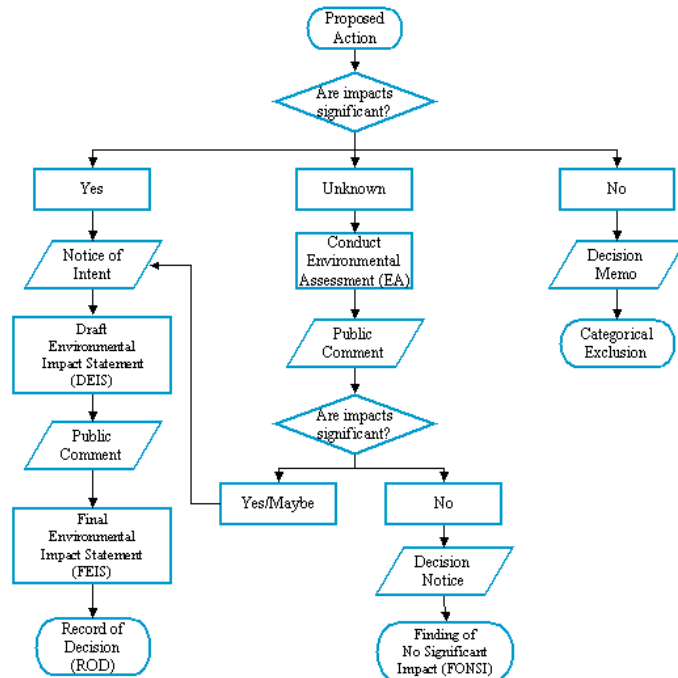
- A **Q**-node represents a single edge
- An **S**-node represents a series composition; its children T_1 and T_2 represent G_1 and G_2
- A **P**-node represents a parallel composition; its children T_1 and T_2 represent G_1 and G_2



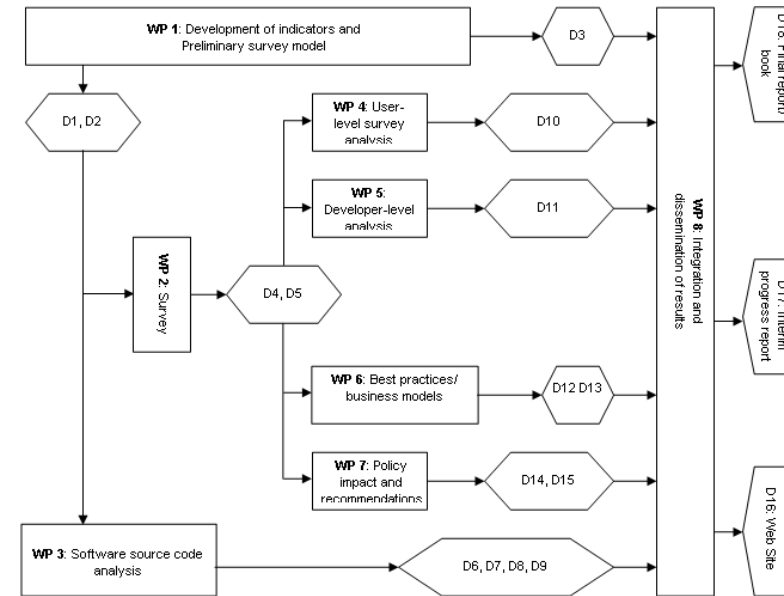
Series-Parallel Graphs – Decomposition Example



Series-Parallel Graphs – Applications



Flowcharts



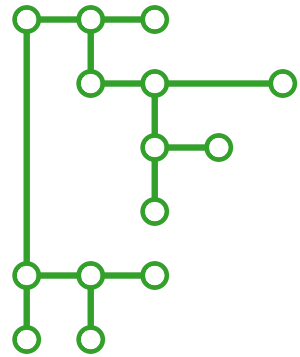
PERT-Diagrams

(Program Evaluation and Review Technique)

Computational complexity:

Linear time algorithms for \mathcal{NP} -hard problems

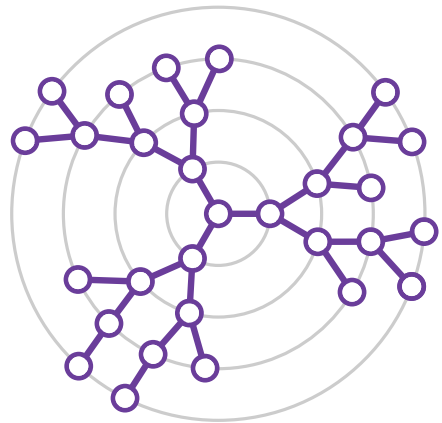
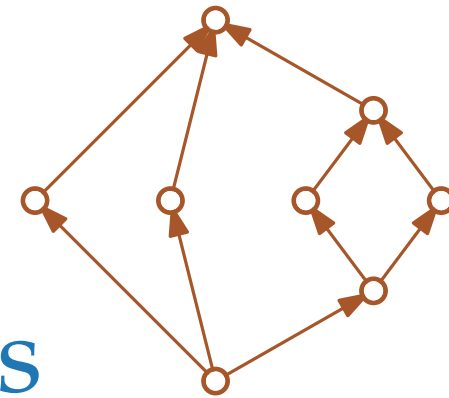
(e.g. Maximum Matching, MIS, Hamiltonian Completion)



Visualization of Graphs

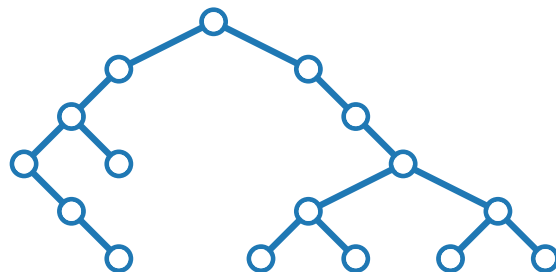
Lecture 2:

Drawing Trees and Series-Parallel Graphs



Part VI:

Drawings of Series-Parallel Graphs



Philipp Kindermann

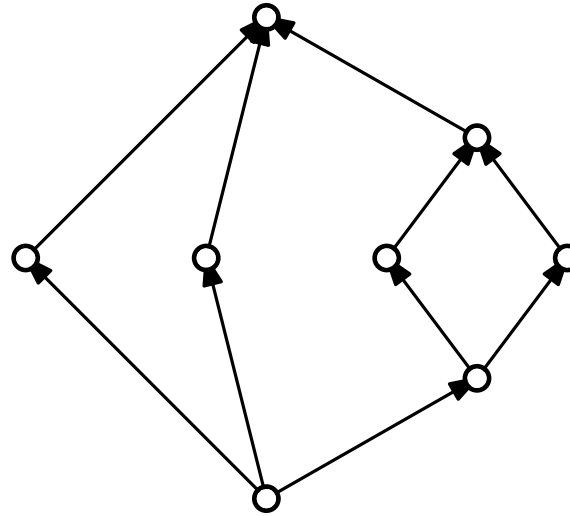
Series-Parallel Graphs – Drawing Style

Drawing conventions

- Planarity
- Straight-line edges
- Upward

Drawing aesthetics

- Area



Series-Parallel Graphs – Straight-Line Drawings

Divide & conquer algorithm using the decomposition tree

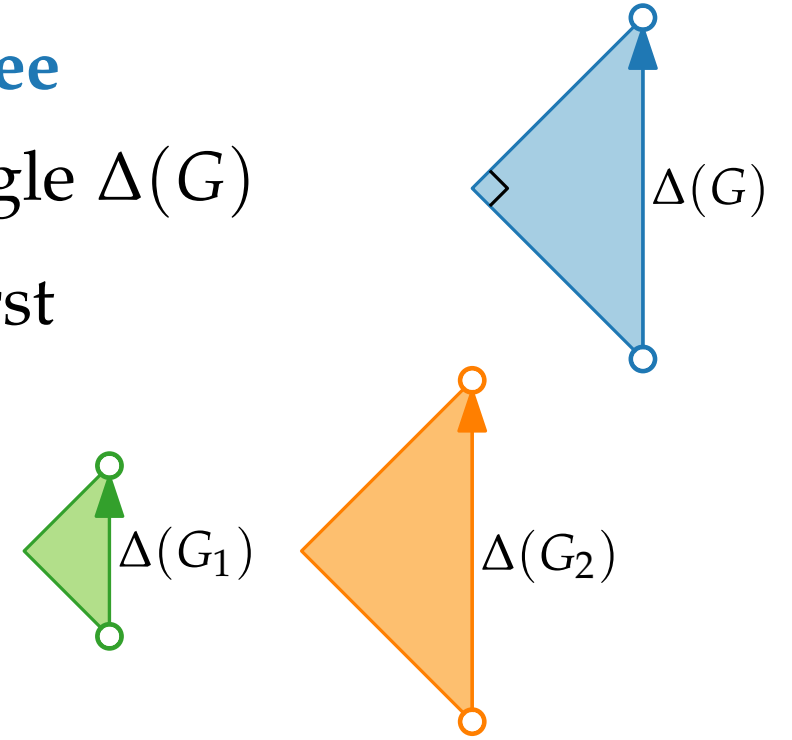
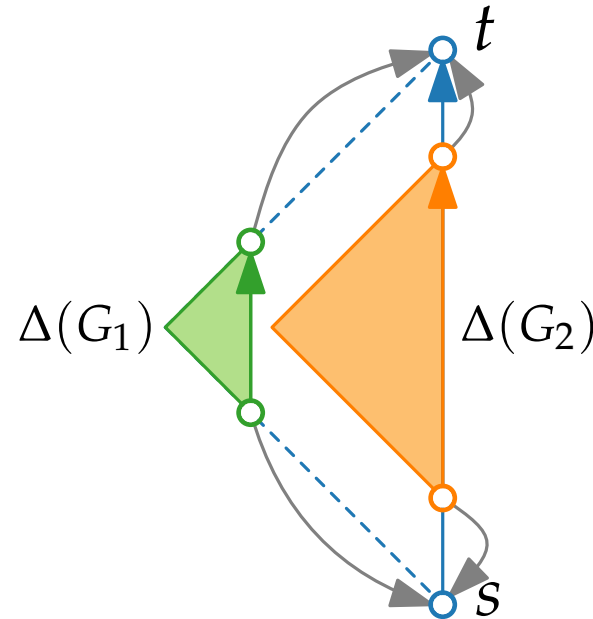
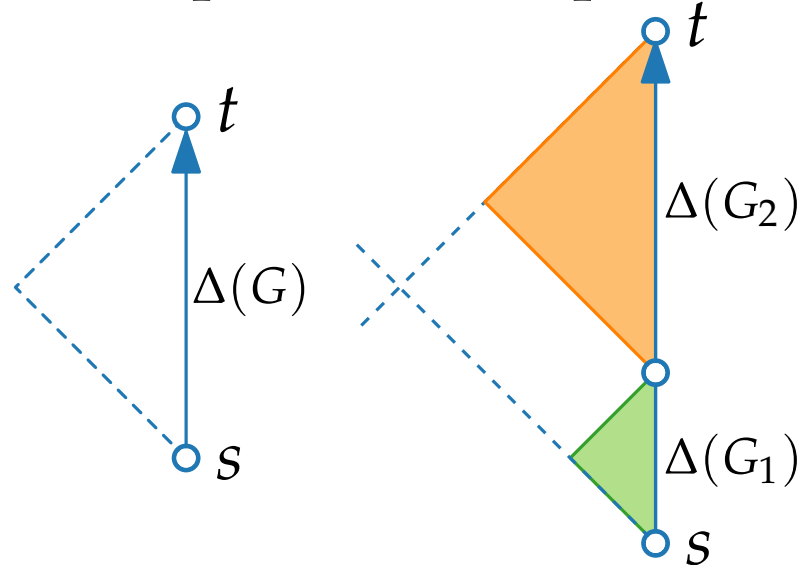
- Draw G inside a right-angled isosceles bounding triangle $\Delta(G)$

Base case: Q-nodes

Divide: Draw G_1 and G_2 first

Conquer:

- S-nodes / series composition
- P-nodes / parallel composition



Do you see any problem?

Series-Parallel Graphs – Straight-Line Drawings

Divide & conquer algorithm using the decomposition tree

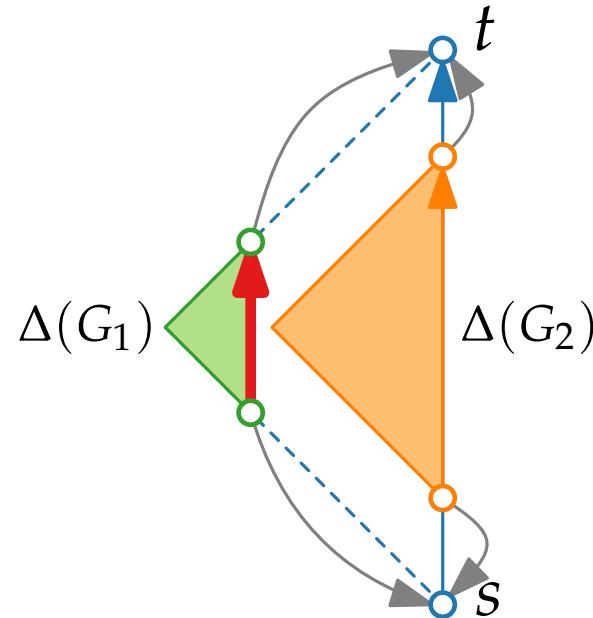
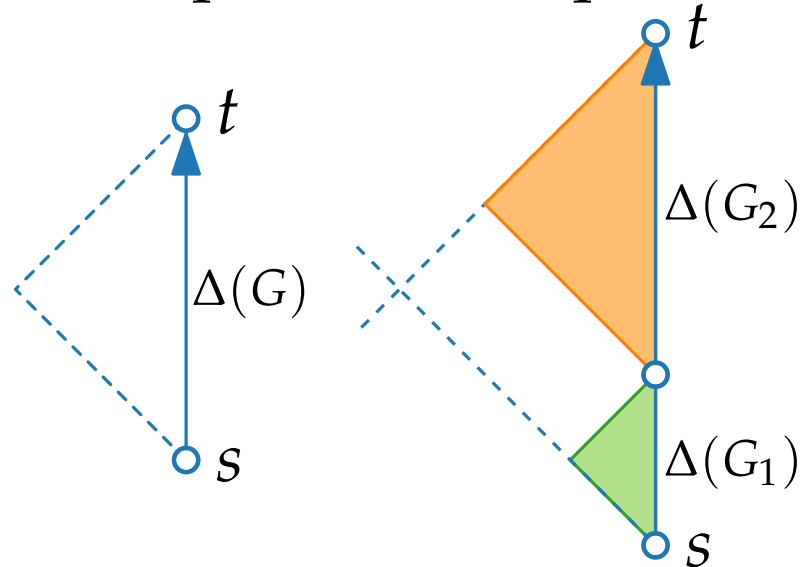
- Draw G inside a right-angled isosceles bounding triangle $\Delta(G)$

Base case: Q-nodes

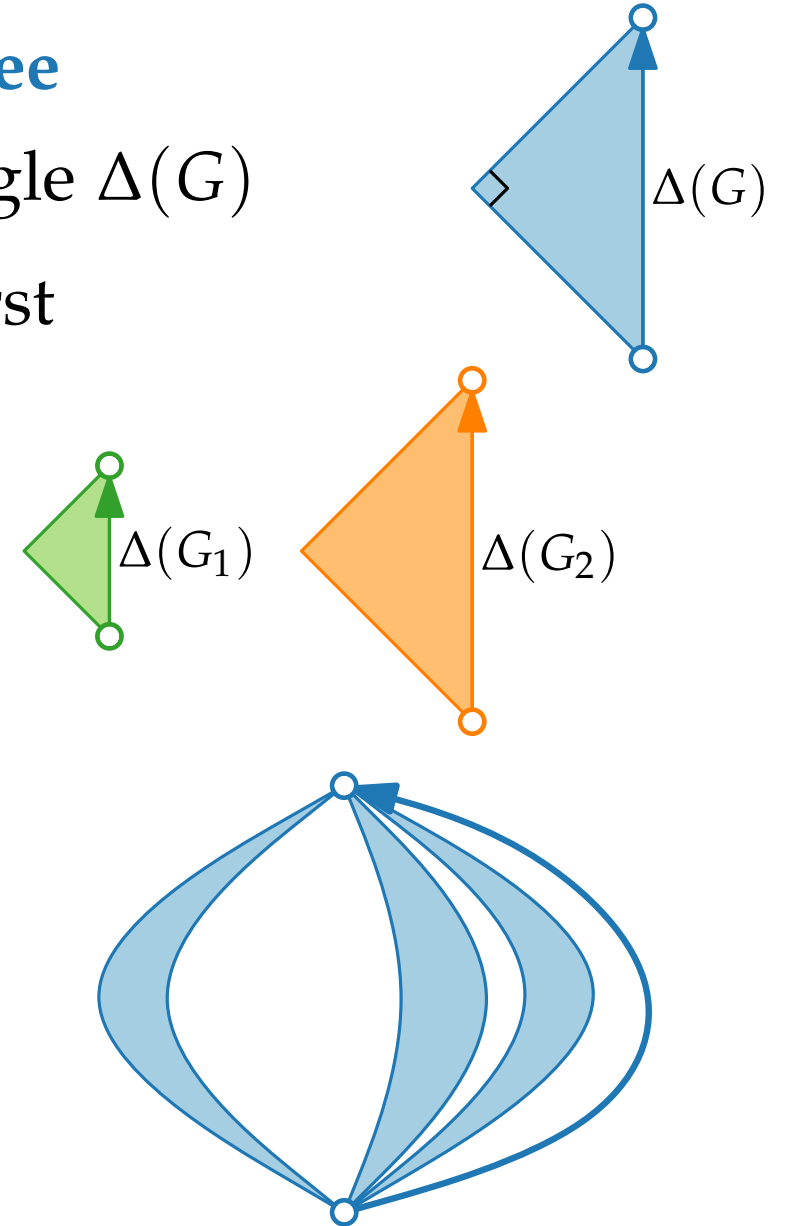
Divide: Draw G_1 and G_2 first

Conquer:

- S-nodes / series composition
- P-nodes / parallel composition

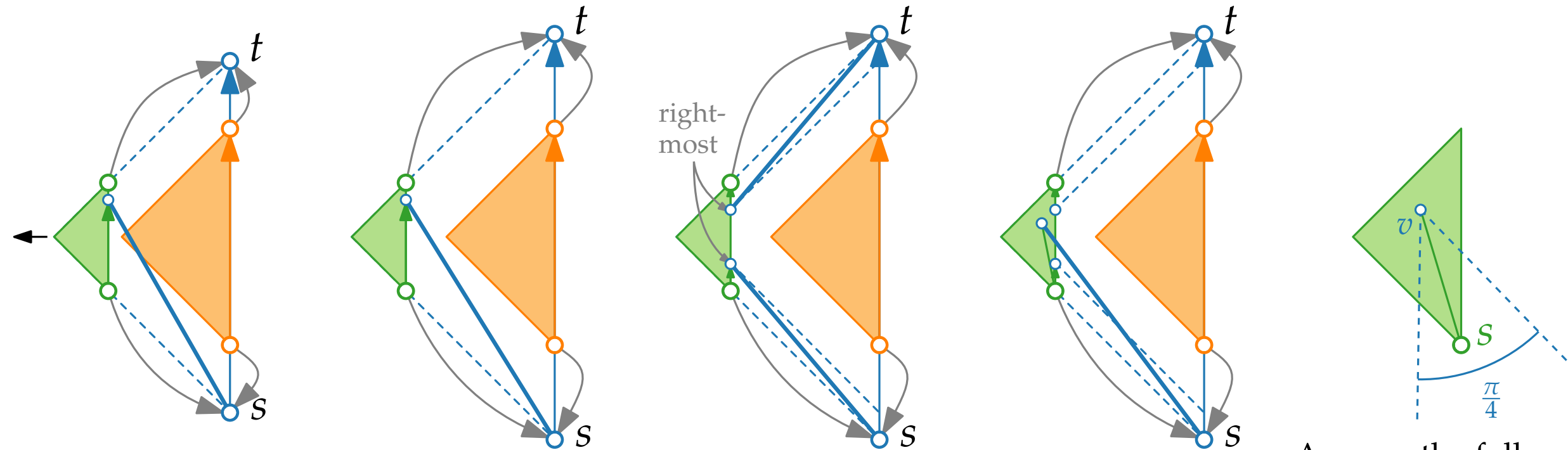


change embedding!



Series-Parallel Graphs – Straight-Line Drawings

- What makes parallel composition possible without creating crossings?



- This condition **is** preserved during the induction step.

Assume the following holds:
the only vertex in $\text{angle}(v)$ is s

Lemma.

The drawing produced by the algorithm is planar.

Series-Parallel Graphs – Result

Theorem.

Let G be a series-parallel graph. Then G (with **variable embedding**) admits a drawing Γ that

- is upward planar and
- a straight-line drawing
- with area in $\mathcal{O}(n^2)$.
- Isomorphic components of G have congruent drawings up to translation.

Γ can be computed in $\mathcal{O}(n)$ time.

Series-Parallel Graphs – Fixed Embedding

Theorem. [Bertolazzi et al. 94]

There exists a $2n$ -vertex series-parallel graph G_n such that any upward planar drawing of G_n that **respects the embedding** requires $\Omega(4^n)$ area.

- $2 \cdot \text{Area}(G_n) < \text{Area}(\Pi)$
- $2 \cdot \text{Area}(\Pi) \leq \text{Area}(G_{n+1})$
- $4 \cdot \text{Area}(G_n) \leq \text{Area}(G_{n+1})$

